

## High Speed Multitasking Computers

High speed industrial multitasking computers integrated in a compact module. BASIC Tigers get used in virtually all kinds of instruments and projects:

- ♦ medical equipment
- ♦ GPS systems
- ♦ GSM systems
- ♦ communication equipment
- ♦ industrial control
- ♦ alarm systems
- ♦ container tracking
- ♦ quality control systems ...

BASIC Tigers offer an exceptional value in terms of

- ♦ short development cycles
- ♦ highest product reliability
- ♦ low cost
- ♦ innovative features

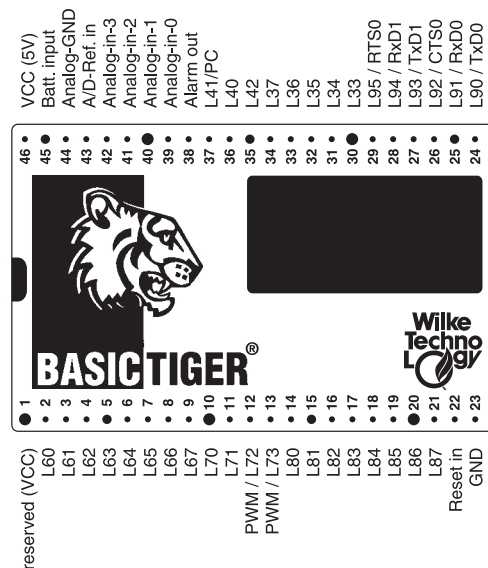
For further information, detailed literature and manuals in printed or downloadable formats visit:

[www.wilke.de](http://www.wilke.de)

or

[www.wilke-technology.com](http://www.wilke-technology.com)

### 640 kB to 6 MB FLASH + SRAM



### ANN-1/4, ACI-4/4, AXI-8/4, ACI-8/32, ...

Sheet

Data

- ♦ Dimensions: approx. 40.6 x 62.2 x 11.4 mm / 1.6 x 2.5 x 0,5"  
46-pin DIP type case  
pin to pin clearance 2.54 mm / 0.1", row distance 35.56 mm / 1,4"  
square pins 0.64 x 0.64 mm / 0.025 x 0.025"
- ♦ Weight: approx. 48g / 1.7 ounce
- ♦ Operating temperature:  
Standard: 0°C to +70°C  
Industrial: -20°C to +85°C  
Expanded: expanded ranges up to -55°C to 105°C on request
- ♦ Power supply: 4.6V - 5.5V / 45-60mA typ.
- ♦ System timebase accuracy: +/-50 ppm base tolerance,  
+/-30 ppm over temp. range -20°C to +70°C  
+/-5 ppm per year max. aging  
Other specifications available optional
- ♦ Reset: Power-ON reset internal, active @Vcc = 4,5V +/- 0.1V  
Reset input: LOW-active, internal pull-up R = 10 KΩ typ.
- ♦ I/O pins: 38 universal I/O-pins

## High Speed Multitasking Computers

♦ Max current for digital outputs:	1.6 mA / pin (low, U=0.45V max) -0.4 mA / pin (high, U=2.4V min) Max. darlington driver current: -3,5 mA (U=1.5V), max 8 pins
♦ Rising time / falling time:	15 ns typ. (10%, 90%)
♦ Impedance digital Inputs:	High-Impedance or additional pull-up / pull-down resistor: L33 ... L37 pull-up 50 ... 150 kΩ L40 ... L41 pull-up 50 ... 150 kΩ L42 pull-down 50 ... 150 kΩ L60 ... L67 pull-up 50 ... 150 kΩ L70...L73 pull-up 50 ... 150 kΩ L80...L87 pull-up 50 ... 150 kΩ L90...L95 pull-up 50 ... 150 kΩ
♦ Digital Inputs:	Input voltage „high“: 0.7 * Vcc min Input voltage „low“: 0.8V max
♦ Analog input:	4 channels
♦ Input range Vref:	Vcc-1.5V ... Vcc
♦ Vref input current:	0.5 mA typ, 1.5 mA max
♦ Impedance analog inputs:	20 kΩ typ., note: low impedance in power down state
♦ Analog input range:	0...Vref
♦ Analog input resolution:	10 bit internal hardware resolution, 12 bit through moving window integration. Linearization and calibration through software function LIN_APPROX and flash calibration tables.
♦ Analog input accuracy:	+/- 0.5 LSB quantize error +/- 1.5 LSB typ, +/- 4 LSB max at normal speed (-20°C ... 70°C) +/- 4.0 LSB typ, +/- 8 LSB max in high speed (-20°C ... 70°C)
♦ Analog sampling rate:	up to 50.000 samples / sec
♦ Analog sampling buffer:	up to 30 kByte
♦ PWM:	2 PWM output channels: 6-bit resolution, 5 / 20 / 80 kHz 7-bit resolution, 4 / 10 / 40 kHz 8-bit resolution, 1.2 / 2.5 / 5 kHz
♦ Memory internal:	128 KB ... 2 MB Static RAM 512 KB ... 4 MB FLASH
♦ Realtime clock	+/-20 ppm base tolerance -0,04 ppm/°C temp. coefficient +/-3 ppm divergence per year software calibration for RTC available  Alarm function: Alarm pin low = active, Alarm pin high = waiting for alarm or no alarm task. Buffered through battery backup input

## High Speed Multitasking Computers

- Battery Backup Input
- Serial channels:

2.7...4.5V,  $I_{Batt} = 50 \dots 300 \mu A$  typ.

2 buffered UART channels:

CH-0: RxD, TxD, RTS, DTR

Baudrates: 300,600,1200, 2400, 4800, 9600, 19200, 38400, 76800, 153600, 614400,

Data/Parity: 7N, 7E, 7O, 8N, 8E, 8O, 9N

Buffer sizes: 256, 512, 1024, 2048, 4096 Bytes

CH-1: as above, RxD and TxD lines

Level systems: 5V or RS-232 I/O-levels

Up to 8 additional serial I/O channels through software driver SER2.TDD.

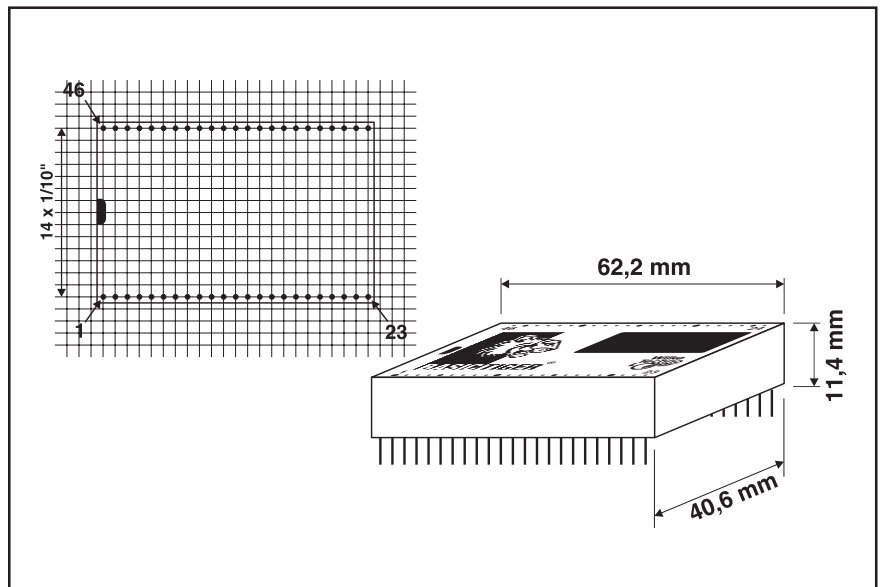
Selectable: RxD, TxD or RxD + TxD per channel

Max baudrate (1 channel): 9600 Bd TxD, 4800 Bd RxD

Max baudrate multi channel: -> divided by no of channels

- Pulses

Resolutions: 0.4 / 1.6 / 6.4 / 50  $\mu s$



BASIC Tiger Computer Modules:

Type	SRAM	FLASH	Serial	Realtime Clock
ANN-1/4	128 KByte	512 KByte	5V	-
ACN-1/4	128 KByte	512 KByte	5V	RTC
AXN-1/4	128 KByte	512 KByte	RS-232	RTC
ACI-4/4	512 KByte	512 KByte	5V	RTC
AXI-4/4	512 KByte	512 KByte	RS-232	RTC
ACI-8/4	1 MByte	512 KByte	5V	RTC
AXI-8/4	1 MByte	512 KByte	RS-232	RTC
ACI-8/32	1 MByte	4 MByte	5V	RTC
ACI-16/32	2 MByte	4 MByte	5V	RTC